

Online Supplement

Probability of ruin within finite time and Cramér–Lundberg inequality for fractional risk processes

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Simulation of the compound fractional risk process

The algorithm for testing the condition $R_\alpha^\bullet(t) < 0$ for $t \in [0, T]$ in the R package can be written as follows.

```
# Input: u, c, lambda, mu, alpha, T, Delta
# Output: IsRuined=TRUE if surplus is negative before time T

# Initialize the ruin indicator to FALSE.
IsRuined = FALSE

# Initialize the total amount paid in claims to 0.
CurrentTotalPay = 0

# Initialize the current time in the inverse subordinator (Yt) to 0.
NextClaimYt = 0
CurrentYt = 0

# Initialize the original time (t) to 0.
Current.t = 0

# The main simulation loop continues as long as the original time is
# within the specified horizon T and ruin has not occurred.
while (Current.t <= T && !IsRuined) {

  # Simulate the next claim arrival time in the classical risk process (gapPP)
  # using an exponential distribution with rate lambda (lam).
  gapPP = rexp(1, lam)

  # Update the time of the next claim in the inverse subordinator's clock.
  NextClaimYt = NextClaimYt + gapPP

  # Initialize a temporary time step for the inverse subordinator.
  Delta0 = Delta
```

```

# This inner loop simulates the inverse alpha-stable subordinator's
# trajectory in small steps to reach the next claim time.
while(CurrentYt < NextClaimYt) {

  # If the remaining distance to the next claim is smaller than the
  # standard time step Delta, adjust the step size to precisely
  # hit the next claim time.
  if(Delta > NextClaimYt - CurrentYt)
    Delta0 = NextClaimYt - CurrentYt

  # Generate two uniform random numbers, U and V, to be used in the
  # Chambers-Mallows-Stuck algorithm for simulating an alpha-stable
  # random variable.
  U = runif(1)
  V = runif(1)

  # Calculate the numerator of the alpha-stable random variable formula.
  numer = sin(alpha * pi * U) * (sin((1 - alpha) * pi * U))^(1/alpha - 1)

  # Calculate the denominator of the alpha-stable random variable formula.
  denom = (sin(pi * U))^(1/alpha) * (abs(log(V)))^(1/alpha - 1)

  # Calculate D1, a positive alpha-stable random variable used to scale
  # the time step in the subordinator.
  D1 = numer / denom

  # Update the original time (t) based on the current step
  # in the inverse subordinator's time.
  Current.t = Current.t + D1 * Delta0^(1/alpha)

  # Advance the time in the subordinator's clock by the step size.
  CurrentYt = CurrentYt + Delta0
}

# Simulate the size of the claim using an exponential distribution
# with mean mu.
CurrentTotalPay = CurrentTotalPay + rexp(1, 1 / mu)

# Calculate the current surplus based on the initial capital (u),
# premium income (c * CurrentYt), and total claims paid.
CurrentSurplus = u + c * CurrentYt - CurrentTotalPay

# Check if the ruin condition is met: the surplus is negative before
# or at the end of the simulation horizon T.
if (Current.t <= T && CurrentSurplus < 0) {
  IsRuined = TRUE
}
}

# Return the boolean value indicating whether ruin occurred.
return(IsRuined)

```

Plotting of the cdf of the Mittag-Leffler distribution

The cdf of the Mittag-Leffler distribution in the R package can be depicted as follows.

```
library(MittagLefflerR)

# ----- Parameters you can adjust -----
alpha_values <- c(1.0, 0.9, 0.7, 0.5, 0.3) # Shape parameters a to compare
curve_colors <- c('black', 'red', 'green', 'blue', 'orange')
line_width <- 2

# Grid on the positive support
t_min <- 0
t_max <- 10
n_points <- 1000L
t_grid <- seq(t_min, t_max, length.out = n_points)

# ----- CDF of the one-parameter Mittag-Leffler distribution -----
# Uses:  $F(t; a) = 1 - E_{\{a\}}(-t^{\{a\}})$ , where  $E_{\{a\}} = E_{\{a,1\}}$ 
cdf_mittag_leffler <- function(t, alpha) {
  1 - mlf(-(t^alpha), alpha)
}

# ----- Open a PDF device -----
pdf("ruin-prob-ml.pdf", width = 7, height = 3)

# Tidy up margins and axis label spacing
par(mar = c(3, 3, 2, 1), mgp = c(1.8, 0.6, 0))

# Initialize an empty plot with proper limits for a CDF
plot(
  NA, xlim = c(t_min, t_max), ylim = c(0, 1.02),
  xlab = "t", ylab = "CDF_{a}F(t;_{a})",
  main = "Mittag-Leffler_{CDF:_{a}F(t)_{a}=1_{a}=E_{a}(-t^{a})",
  xaxs = "i", yaxs = "i"
)

# Draw CDF curves for each a
for (i in seq_along(alpha_values)) {
  alpha_i <- alpha_values[i]
  F_vals <- cdf_mittag_leffler(t_grid, alpha_i)
  lines(t_grid, F_vals, col = curve_colors[i], lwd = line_width)
}

# Legend
legend("bottomright",
  legend = sprintf("a_{a}=%g", alpha_values),
  col = curve_colors, lwd = line_width, bty = "n", title = "Shape")

# Close the device
dev.off()
```

Plotting of the finite-time ruin probability

The finite-time ruin probability $\psi^\alpha(t)$ for the compound fractional risk model in the R package can be depicted as follows.

```
library(MittagLefflerR)

# -----
# Integrand for the ruin probability integral
# -----
ruin_integrand <- function(x, t, u, lambda_rate, mu_mean, premium_rate, alpha) {
  # x can be a vector; all others are scalars
  stopifnot(is.numeric(x), length(t) == 1L, length(u) == 1L,
            length(lambda_rate) == 1L, length(mu_mean) == 1L,
            length(premium_rate) == 1L, length(alpha) == 1L)

  beta <- (lambda_rate * mu_mean) / premium_rate
  u_over_mu <- u / mu_mean
  sqrt_beta <- sqrt(beta)

  # Components of the integrand
  sb_cosx <- sqrt_beta * cos(x)
  # z for the Mittag-Leffler function E_{a,1}(z)
  z <- (2 * sb_cosx - (1 + beta)) * (premium_rate / mu_mean) * (t^alpha)

  # E_{a,1}(z)
  Ea1 <- mlf(z, alpha) # MittagLeffler::mlf(x, alpha) = E_{a,1}(x)

  expo <- beta * exp(u_over_mu * (sb_cosx - 1))
  u_sb_sinx <- u_over_mu * sqrt_beta * sin(x)

  num <- Ea1 * expo * (cos(u_sb_sinx) - cos(u_sb_sinx + 2 * x))
  den <- (1 + beta - 2 * sb_cosx)

  # Prevent numerical blow-ups near the singular set by softening very small |den|
  # (this leaves the limit behavior well-behaved for numerical integration)
  den_safe <- ifelse(abs(den) < 1e-12, sign(den) * 1e-12, den)

  num / den_safe
}

# -----
# Single-time finite-time ruin probability
# -----
ruin_prob_single <- function(t, u, lambda_rate, mu_mean, premium_rate, alpha,
                             rel.tol = 1e-8, abs.tol = 1e-10, subdivisions = 2000L) {
  stopifnot(t >= 0, u > 0, lambda_rate > 0, mu_mean > 0, premium_rate > 0,
            alpha > 0, alpha <= 1)

  beta <- (lambda_rate * mu_mean) / premium_rate
  p_infty <- beta * exp(-(1 - beta) * (u / mu_mean)) # infinite-horizon term

  I <- integrate(
    f           = ruin_integrand,
    lower       = 0, upper = pi,
    t           = t, u = u,
    lambda_rate = lambda_rate,
```

```

    mu_mean      = mu_mean,
    premium_rate = premium_rate,
    alpha        = alpha,
    rel.tol      = rel.tol,
    abs.tol      = abs.tol,
    subdivisions = subdivisions,
    stop.on.error = FALSE
  )

  if (!is.null(I$message) && grepl("Error", I$message, fixed = TRUE)) {
    warning(sprintf(
      "Integration warning at t=%.4g, a=%.3f: %s", t, alpha, I$message))
  }

  p_infty - (I$value / pi)
}

# Vectorized wrapper over a grid of times
ruin_prob_vec <- function(t_grid, u, lambda_rate, mu_mean, premium_rate, alpha,
  rel.tol = 1e-8, abs.tol = 1e-10, subdivisions = 2000L) {
  vapply(
    t_grid,
    function(tt) ruin_prob_single(
      t = tt, u = u, lambda_rate = lambda_rate, mu_mean = mu_mean,
      premium_rate = premium_rate, alpha = alpha,
      rel.tol = rel.tol, abs.tol = abs.tol, subdivisions = subdivisions
    ),
    numeric(1L)
  )
}

# -----
# Plotting function
# -----
make_ruin_plot <- function(
  file_name,
  t_grid,
  u,
  lambda_rate,
  mu_mean,
  premium_rate,
  alpha_values = c(1.0, 0.9, 0.7, 0.5, 0.3),
  y_lower_scale = 0.8, # lower y bound fraction of the max across curves
  curve_colors = c("black", "red", "green", "blue", "orange"),
  line_width = 2
) {
  stopifnot(length(alpha_values) <= length(curve_colors))

  # Precompute curves so we can set a consistent y-range
  curves <- lapply(alpha_values, function(a)
    ruin_prob_vec(t_grid, u, lambda_rate, mu_mean, premium_rate, alpha = a)
  )
  y_max <- max(vapply(curves, max, numeric(1), na.rm = TRUE))
  ylim <- c(y_lower_scale * y_max, 1.00 * y_max)

  # Open device
  pdf(file_name, width = 7, height = 3)
  on.exit(dev.off(), add = TRUE)
}

```

```

par(mar = c(3, 3, 2.5, 6), xpd = TRUE, mgp = c(1.8, 0.6, 0))

# Draw first curve
plot(
  t_grid, curves[[1]],
  type = "l", lwd = line_width, col = curve_colors[1],
  xlab = "t", ylab = "Ruin_probability",
  ylim = ylim, xaxs = "i", yaxs = "i",
  main = "CFR-model_finite-time_ruin_probability"
)

# Add remaining curves
if (length(alpha_values) > 1) {
  for (i in 2:length(alpha_values)) {
    lines(t_grid, curves[[i]], col = curve_colors[i], lwd = line_width)
  }
}

# Legend on the right
legend(
  "right",
  legend = sprintf("a=%g", alpha_values),
  inset = -0.2, lwd = line_width, col = curve_colors,
  title = "alpha", bty = "n"
)

# Parameter annotation
beta <- (lambda_rate * mu_mean) / premium_rate
mtext(
  sprintf("u=%g, lambda=%g, mu=%g, c=%g, beta=%g",
    u, lambda_rate, mu_mean, premium_rate, beta),
  side = 3, line = -0.05, cex = 0.9
)
}

# Time grid (same structure as your original)
t_grid <- sort(c(seq(1, 2, by = 0.1), seq(2.5, 10, by = 0.5)))

# Common parameters
lambda_rate <- 45
mu_mean <- 50

# 1) Baseline
u <- 250
premium_rate <- 3000
make_ruin_plot("ruin-prob-ml-ft.pdf", t_grid,
  u, lambda_rate, mu_mean, premium_rate)

# 2) Different initial reserve u
u <- 100
make_ruin_plot("ruin-prob-ml-ft2.pdf", t_grid,
  u, lambda_rate, mu_mean, premium_rate, y_lower_scale = 0.89)

# 3) Different premium rate
u <- 250
premium_rate <- 2500
make_ruin_plot("ruin-prob-ml-ft3.pdf", t_grid,
  u, lambda_rate, mu_mean, premium_rate, y_lower_scale = 0.60)

```

Plotting of the density of the inverse subordinator

The density of $Y_\alpha(1)$ in the R package can be depicted as follows.

```
library(MWright)

# -----
# 1) Series kernel g_a(z) for a single z
# -----
g_alpha_single <- function(z, alpha, n_terms = 120L) {
  # z: positive scalar
  # alpha: in (0,1]
  # n_terms: number of series terms

  if (!is.numeric(z) || length(z) != 1L || z <= 0) {
    stop("g_alpha_single() expects a single positive z.")
  }
  if (!(alpha > 0 && alpha <= 1)) {
    stop("alpha must be in (0,1].")
  }

  k <- seq_len(n_terms)

  # Use lgamma to prevent overflow in gamma(alpha*k+1)/gamma(k+1)
  coeff <- exp(lgamma(alpha * k + 1) - lgamma(k + 1))
  signs <- (-1)^(k + 1)
  terms <- signs * coeff * sin(pi * alpha * k) / (z^(alpha * k + 1))

  sum(terms) / pi
}

# -----
# 2) Inverse a-stable density via the g_a kernel
# -----
dinv_alpha_stable <- function(x, alpha, n_terms = 120L) {
  # Vectorized in x.
  # For x <= 0, the density is 0 on this support.
  if (!(alpha > 0 && alpha <= 1)) {
    stop("alpha must be in (0,1].")
  }

  inv_alpha <- 1 / alpha
  out <- numeric(length(x))

  positive_idx <- which(x > 0)
  if (length(positive_idx) > 0) {
    x_pos <- x[positive_idx]
    # z = 1 / x^{1/alpha}
    z_vals <- x_pos^(-inv_alpha)
    g_vals <- sapply(z_vals, g_alpha_single, alpha = alpha, n_terms = n_terms)
    out[positive_idx] <- inv_alpha * g_vals / (x_pos^(1 + inv_alpha))
  }

  out
}

# -----
```

```

# Common plotting parameters
# -----
alpha_values <- c(0.95, 0.9, 0.7, 0.5, 0.3)
curve_colors <- c("black", "red", "green", "blue", "orange")
line_width <- 2

# x-grid used in both figures
x_min <- 1 / 200 # = 0.005 (matches your original grid start)
x_max <- 5
n_points <- 1000L
x_grid <- seq(x_min, x_max, length.out = n_points)

# -----
# FIGURE 1: Inverse a-stable density via series
# -----
# Precompute all curves to set a consistent ylim
ias_curves <- lapply(alpha_values,
  function(a) dinv_alpha_stable(x_grid, a, n_terms = 120L))
ias_ymax <- max(vapply(ias_curves, max, numeric(1), na.rm = TRUE))
ylim_ias <- c(0, max(3.2, 1.05 * ias_ymax))

pdf("dens-ias.pdf", width = 7, height = 3)
par(mar = c(3, 3, 2, 1), mgp = c(1.8, 0.6, 0)) # margins and axis spacing

# Draw the first curve
plot(
  x_grid, ias_curves[[1]],
  type = "l", lwd = line_width, col = curve_colors[1],
  xlab = "x", ylab = "Density",
  main = "Inverse a-stable density (series approximation)",
  ylim = ylim_ias, xaxs = "i", yaxs = "i"
)

# Add the rest
for (i in 2:length(alpha_values)) {
  lines(x_grid, ias_curves[[i]], col = curve_colors[i], lwd = line_width)
}

legend("topright",
  legend = sprintf("a = %g", alpha_values),
  col = curve_colors, lwd = line_width, bty = "n", title = "Shape")
dev.off()

# -----
# FIGURE 2: Inverse a-stable density via MWright::dmwright1
# -----
# dmwright1(alpha, scale, n_points, x_max) returns a 2-col matrix [x, f(x)]
mw_curves <- lapply(alpha_values, function(a) {
  xy <- dmwright1(a, 1, n_points, x_max)
  # Ensure it's a 2-column object: x in col 1, density in col 2
  as.matrix(xy)
})

mw_ymax <- max(vapply(mw_curves,
  function(m) max(m[, 2], na.rm = TRUE), numeric(1)))
ylim_mw <- c(0, max(3.2, 1.05 * mw_ymax))

pdf("dens-fmwf.pdf", width = 7, height = 3)
par(mar = c(3, 3, 2, 1), mgp = c(1.8, 0.6, 0))

```

```

# First curve
plot(
  mw_curves[[1]][, 1], mw_curves[[1]][, 2],
  type = "l", lwd = line_width, col = curve_colors[1],
  xlab = "x", ylab = "Density",
  main = "Inverse  $\alpha$ -stable density via (MWright::dmwright1)",
  ylim = ylim_mw, xaxs = "i", yaxs = "i"
)

# Remaining curves
for (i in 2:length(alpha_values)) {
  lines(mw_curves[[i]][, 1], mw_curves[[i]][, 2],
        col = curve_colors[i], lwd = line_width)
}

legend("topright",
       legend = sprintf("a= $\alpha$ %g", alpha_values),
       col = curve_colors, lwd = line_width, bty = "n", title = "Shape")
dev.off()

```

Plotting trajectories of the inverse subordinator

The random trajectories of $Y_\alpha(t)$ in the R package can be depicted as follows.

```
r_pos_stable <- function(n, alpha, u_eps = 1e-12) {
  stopifnot(is.numeric(n), n >= 1, is.finite(n),
            is.numeric(alpha), length(alpha) == 1L, alpha > 0, alpha < 1)

  inv_alpha <- 1 / alpha
  # Avoid U exactly at {0, pi} to prevent sin() under/overflow
  U <- runif(n, min = u_eps, max = pi - u_eps) # U in (0, pi)
  E <- rexp(n) # E ~ Exp(1)

  num <- sin(alpha * U) * (sin((1 - alpha) * U))^(inv_alpha - 1)
  den <- (sin(U))^inv_alpha * (E)^(inv_alpha - 1)

  x <- num / den
  # Theoretically X > 0; clamp any tiny negatives due to floating error
  pmax(x, 0)
}

# -----
# Simulate one a-stable subordinator path D(s)
# -----
# Discrete grid s_k = k * dt, k = 0, 1, ..., n_steps-1 (length n_steps).
# D(0) = 0, and increments are scaled as dt^{1/a}.
simulate_subordinator_path <- function(dt, n_steps, alpha) {
  stopifnot(is.numeric(dt), dt > 0, n_steps >= 2)
  # n_steps points => (n_steps - 1) increments
  inc <- dt^(1 / alpha) * r_pos_stable(n_steps - 1, alpha)
  c(0, cumsum(inc))
}

# -----
# Make multi-page PDF: one page per a, with multiple sample paths
# -----
make_inv_subordinator_plots <- function(
  file_name = "inverse-stable-subordinator.pdf",
  alpha_values = c(0.99, 0.95, 0.90, 0.70),
  dt = 0.01, # time step for the subordinator's clock s
  s_horizon = 2.0, # max "operational time" s
  n_paths_per_alpha = 50, # how many paths per a (plus a base one)
  seed_per_alpha = 137, # set.seed() before each a (reproducible pages)
  xlim_fixed = NULL, # e.g. c(0, 6); if NULL, determined per page
  base_path_lwd = 2, # thicker line for the first path
  other_paths_lwd = 1, # thinner lines for the remaining paths
  col_palette_fun = function(n) grDevices::hcl.colors(n, "Dark_3") # colors
) {
  stopifnot(is.character(file_name), length(file_name) == 1L)
  stopifnot(all(alpha_values > 0 & alpha_values < 1))
  stopifnot(dt > 0, s_horizon > 0, n_paths_per_alpha >= 1)

  n_steps <- as.integer(round(s_horizon / dt)) + 1L
  s_grid <- dt * (0:(n_steps - 1)) # "physical" time for the inverse (y-axis)

  # Open PDF device
  pdf(file_name, width = 7, height = 3)
```

```

on.exit(dev.off(), add = TRUE)
par(mar = c(3, 3, 2.2, 1), mgp = c(1.8, 0.6, 0))

for (alpha in alpha_values) {
  # Reproducibility per page (same RNG state across a runs)
  if (!is.null(seed_per_alpha)) set.seed(seed_per_alpha)

  # Colors for paths (first path highlighted)
  cols <- col_palette_fun(n_paths_per_alpha + 1L)
  cols[1] <- "black" # first path in black

  # Simulate first (base) path
  D_base <- simulate_subordinator_path(dt, n_steps, alpha)

  # Optionally determine x-limits per page, based on a small pilot set
  if (is.null(xlim_fixed)) {
    D_max <- max(D_base)
    # simulate a few more to get a robust x-maximum (without drawing yet)
    pilot <- 10L
    for (i in seq_len(min(pilot, n_paths_per_alpha))) {
      D_tmp <- simulate_subordinator_path(dt, n_steps, alpha)
      D_max <- max(D_max, D_tmp)
    }
    xlim_use <- c(0, D_max * 1.05)
  } else {
    xlim_use <- xlim_fixed
  }

  # --- Draw base path (as inverse:  $x = D(s)$ ,  $y = s$ ) ---
  plot(
    x = D_base, y = s_grid, type = "s",
    xlim = xlim_use, ylim = c(0, s_horizon),
    xlab = expression(D(s)), ylab = "s",
    main = bquote("Inverse_#alpha-stable_subordinator"),
    col = cols[1], lwd = base_path_lwd, xaxs = "i", yaxs = "i"
  )

  # Draw additional paths
  for (i in seq_len(n_paths_per_alpha)) {
    D_i <- simulate_subordinator_path(dt, n_steps, alpha)
    lines(D_i, s_grid, type = "s",
          col = cols[i + 1L], lwd = other_paths_lwd)
  }

  # Annotate a on the page
  mtext(bquote(alpha == .(alpha)), side = 3, line = 0.1, adj = 0)
}
}

make_inv_subordinator_plots(
  file_name = "invsubord.pdf",
  alpha_values = c(0.99, 0.95, 0.90, 0.70),
  dt = 0.01,
  s_horizon = 2.0,
  n_paths_per_alpha = 50,
  seed_per_alpha = 137,
  xlim_fixed = c(0, 6) # set to NULL for auto-scaling per a
)

```