

Supplementary Information

Templated dewetting of single-crystal, ultra-long nano-wires and on-chip silicon circuits

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SUPPLEMENTARY NOTE 1: PHASE-FIELD MODEL AND SIMULATIONS

Phase field simulations were performed exploiting the model reported in Refs. 18 and 19. A diffused domain approach is considered by accounting for the dynamics of an order parameter, $\varphi(\mathbf{x})$, with $\mathbf{x} \in \Omega$ and Ω the entire simulation domain. It is set to be $\varphi = 1$ in the solid and $\varphi = 0$ with a continuous variation in between described by

$$\varphi = \frac{1}{2} \left[1 - \tanh \left(\frac{3d(\mathbf{x})}{\epsilon} \right) \right]. \quad (1)$$

ϵ is the interface thickness between phases while $d(\mathbf{x})$ is the signed distance from the surface of the solid phase. The latter is identified as the $\varphi = 0.5$ isosurface. The model is based on the definition of an energy functional

$$F[\varphi] = \int_{\Omega} \gamma(\hat{\mathbf{n}}) \left(\frac{\epsilon}{2} |\nabla \varphi|^2 + \frac{1}{\epsilon} B(\varphi) \right) d\mathbf{x} + \int_{\Omega} \frac{\beta}{2\epsilon} \left(-\epsilon \nabla^2 \varphi + \frac{1}{\epsilon} B'(\varphi) \right) d\mathbf{x}, \quad (2)$$

with $B(\varphi) = 18\varphi^2(1-\varphi)^2$. $\gamma(\hat{\mathbf{n}})$ is the surface energy density with $\hat{\mathbf{n}} = -\nabla \varphi / |\nabla \varphi|$ the outward normal of the surface of the solid phase. The first integral of Eq. (2) accounts for the surface energy within the diffused approach, while the second one is the Willmore regularization, considered in order to tackle strong anisotropy regimes by producing rounding of the corners of faceted shapes over a region whose radius is scaling as $\sqrt{\beta}$ ^{18,19}. The evolution law for φ reads

$$\frac{\partial \varphi}{\partial t} = M(\varphi) \nabla^2 \frac{\delta F}{\delta \varphi}, \quad (3)$$

with $M(\varphi) = (2M_0/\epsilon)B(\varphi)$, M_0 a diffusivity constant and $\delta F/\delta \varphi$ the functional derivative of F with respect to φ . These equations are solved by using the Finite Element toolbox AMDiS^{20,21}, exploiting adaptive timestep and spatial discretization. More details about the implementation and numerics can be found in Refs. 19, 22, and 23.

Following Refs. 19, 24, and 25 we define the surface energy density as

$$\gamma(\hat{\mathbf{n}}) = \gamma_0 \left[1 - \sum_i^N \alpha_i (\hat{\mathbf{n}} \cdot \hat{\mathbf{m}}_i)^{w_i} \Theta(\hat{\mathbf{n}} \cdot \hat{\mathbf{m}}_i) \right], \quad (4)$$

with $\hat{\mathbf{m}}_i$ the preferential orientation, i.e. the orientations along which the surface-energy density has minima, α_i controlling the depth of energy minima, w_i controlling the range of orientations affected by a specific energy minimum and N the number of different minima. As in Ref. 25 we set the coefficient α_i in order to reproduce the main facets of Si crystals. In particular, we set

$$\alpha_i = 1 - \left(\frac{\gamma_i}{\gamma_{\langle 001 \rangle}} \right) (1 - \alpha_{\langle 001 \rangle}), \quad (5)$$

with $\alpha_{\langle 001 \rangle}$ a reference parameter. γ_i corresponding to the preferential orientations, namely $\langle 113 \rangle$, $\langle 111 \rangle$, and $\langle 110 \rangle$ and $\langle 001 \rangle$, are taken from Ref. 26. For isotropic evolution $\gamma(\hat{\mathbf{n}}) = \gamma_0$, and γ_0 would only affect the timescale of the process. The isotropic simulation reported in the main text are obtained by setting γ_0 as the average of the γ_i values entering Eq. (5). For anisotropic surface energies the differences between γ_0 and $\gamma_0 \alpha_{\langle 001 \rangle}$ directly affects the strength of the anisotropy. However, from a physical point of view, γ_0 would correspond to the maximum value of the surface-energy density that it is typically unknown or difficult to be determined. In order to reproduce a faceted profile for Si we considered $\gamma_{\langle 001 \rangle} \sim 8.7$ eV/nm² as in Ref. 26. Then we arbitrarily set $\alpha_{\langle 001 \rangle} = 0.05$ and, in turn, $\gamma_0 = 9.15$ eV/nm² because when $\hat{\mathbf{n}} = [001]$ we have $\gamma(\hat{\mathbf{n}}) = \gamma_{\langle 001 \rangle} = \gamma_0(1 - \alpha_{\langle 001 \rangle})$. Therefore, $\alpha_{\langle 001 \rangle}$ is a parameter controlling the anisotropy degree and it has been validated a posteriori by the comparison with experiments. However, it is worth mentioning that higher degree of anisotropy would lead to more expensive simulations and exploring different degrees of anisotropy was far from the scope of the present work. The Willmore regularization parameter β is here set to 0.005. Timescale of the simulations in the main text is arbitrary.

SUPPLEMENTARY NOTE 2: SPONTANEOUS DEWETTING

Spontaneous solid state dewetting of a 12 nm thick UT-SOI can be triggered by impurities on the sample surface (Supplementary Figure 1) or from defects in the BOX as shown in reference 27. Another source of disorder found on all the samples²² are small tips on the BOX surface and at the islands edges (respectively white and yellow arrows in Supplementary Figure 1 e)) where the surface is slightly deformed with respect to the conventional facets.

Orientation dependent dewetting: complement to the cases shown in Fig. 4 in the main text

It has been shown that is possible to control the dewetting dynamics of UT-SOI in order to form ordered arrays of isolated islands and complex nano-architectures by creating *ad hoc* dewetting fronts prior to annealing.^{22,28–32} However, due to the intrinsic anisotropy and stiffness of silicon, a well-controlled outcome can be only obtained for relatively small patches, extending over a few micrometer length (patch height over lateral width, $h/w \sim 1/400$) and strictly oriented along the stable dewetting fronts (the [110] and [1-10] in-plane crystallographic directions). In fact, when cutting the UT-SOI in other directions (e.g. the [010], S.I.) the film rapidly evolves in finger-like projections and then in isolated islands, as for the spontaneous dewetting case. This is illustrated in Supplementary Figure 2 where a drastic change in the number of islands per patch is found when moving from the stable front (0 degrees), to the unstable one (45 degrees).

However, for lower dewetting temperature and annealing time, it is possible to avoid the onset of the Plateau-Rayleigh instability^{33,34} thus obtaining long and connected wires. Examples of split and inter-connected wires forming a complex circuit are shown in the Supplementary Figure 3 that complement the case shown in the main text Fig. 4.

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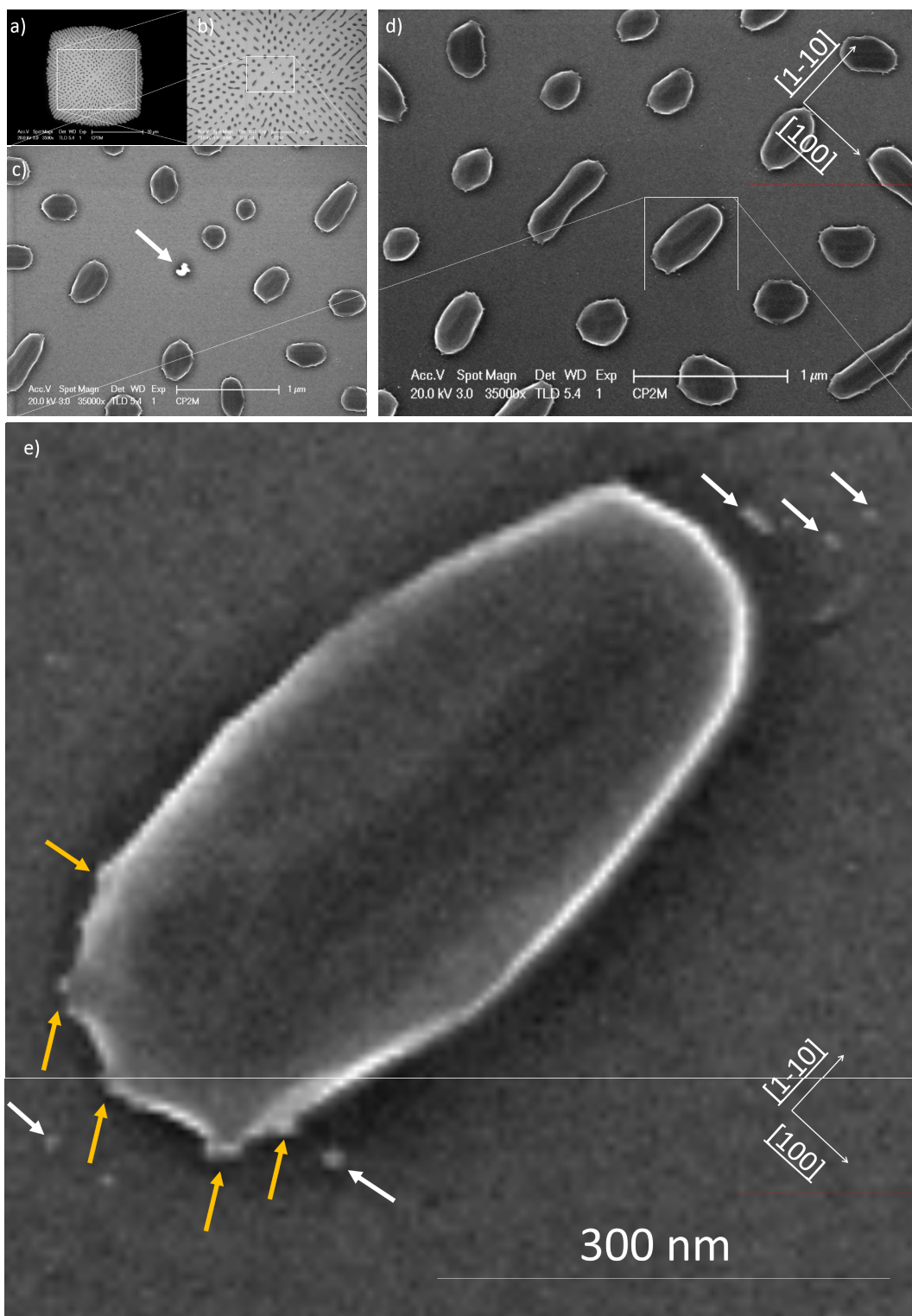
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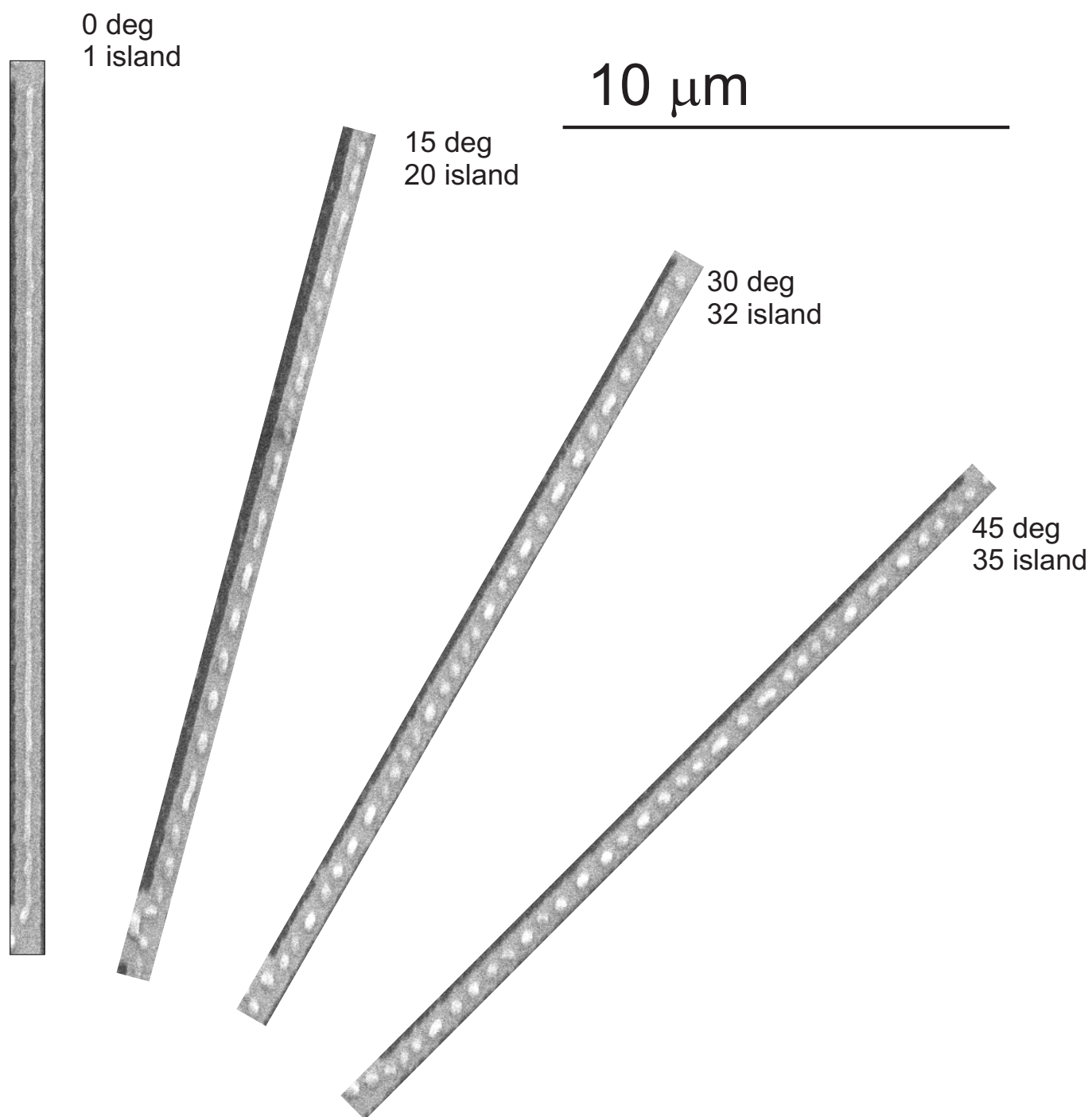
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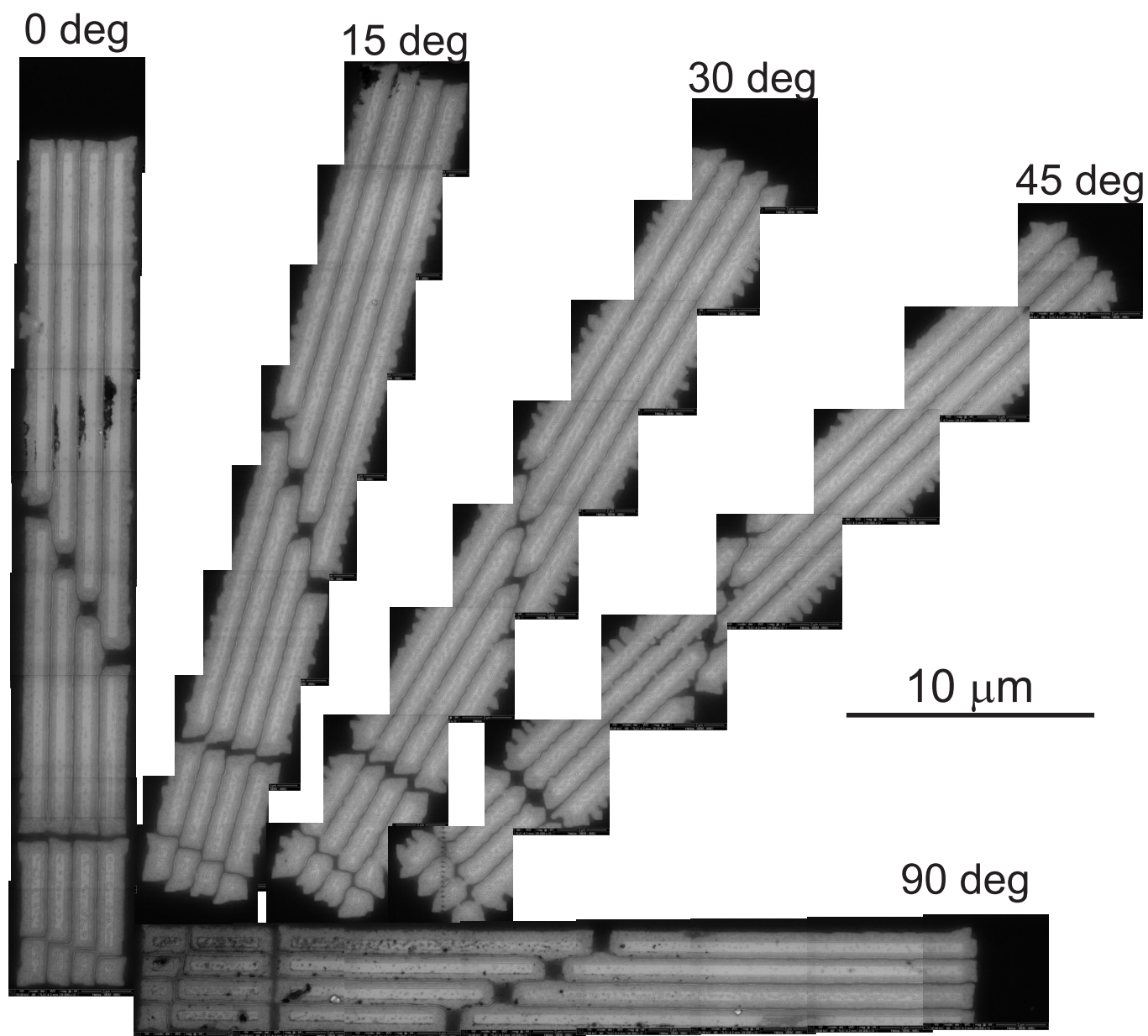
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Supplementary Figure 1. SEM images of a spontaneously dewetted sample (see details in reference 27). a) Large view of a dewetted area in a sample dewetted at 780°C for 120 minutes. b) Blow up of the central area of a). c) Blow up of the central area of b). The white arrow highlight the point where the dewetting started, in presence of an impurity. More details about the starting points of spontaneous dewetting are provided in reference 27. d) High-resolution SEM of the the same sample shown in a). e) Blow up of one island from d). The white arrows highlight small tips on the denuded BOX, whereas the yellow ones highlight those in contact with the edge of the islands.



Supplementary Figure 2. SEM image of a 20 μm long patches oriented along different directions with respect to the stable [110] dewetting front taken as reference (0 degrees).



Supplementary Figure 3. Complement to the cases shown in Fig. 4 in the main text. Arrays composed of 3 wires interconnected and split etched at different orientations (changed in 15 degrees steps) with respect to the [110] direction. In this case the dewetting was induced annealing at 740 °C for 15 minutes.²²