

Supplementary Materials

Passive and Active Triaxial Wall Mechanics in a Two-Layer Model of Porcine Coronary Artery

Yuan Lu¹, Hao Wu², Jiahang Li², Yanjun Gong¹, Jiahui Ma⁴, Ghassan S. Kassab³,
Yong Huo¹, Wenchang Tan^{2,5,6}, and Yunlong Huo^{2,6}

¹*Department of Cardiology, Peking University First Hospital, Beijing, China*

²*Department of Mechanics and Engineering Science, College of Engineering, Peking University, Beijing, China*

³*California Medical Innovations Institute, San Diego, USA*

⁴*School of Public Health, Peking University, Beijing, China*

⁵*Shenzhen Graduate School, Peking University, Shenzhen, China*

⁶*PKU-HKUST Shenzhen-Hongkong Institution, Shenzhen, China*

Running Title: Active and passive mechanical properties of coronary artery

APPENDIX A

Biomechanical principles: In cylindrical coordinate with R, Z, Θ for stress-free state and r, z, θ for no-load and loaded states, we obtain the following expression:

$$r = r(R), \quad \theta = \frac{\pi}{\pi - \varphi} \Theta = \chi \Theta, \quad Z = \lambda_z z \quad (\text{A1})$$

where $\chi = \frac{\pi}{\pi - \varphi}$ is a parameter that characterizes the deformation from stress-free to loaded states depending on the opening angle φ . As the shear deformation is neglected, deformation gradient and green strain tensor are written as:

$$F = \begin{bmatrix} \lambda_r & 0 & 0 \\ 0 & \lambda_\theta & 0 \\ 0 & 0 & \lambda_z \end{bmatrix} = \begin{bmatrix} \frac{dr}{dR} & 0 & 0 \\ 0 & \frac{\chi r}{R} & 0 \\ 0 & 0 & \lambda_z \end{bmatrix} \quad (\text{A2})$$

$$E = \frac{1}{2} [F^T F - 1] = \begin{bmatrix} E_{rr} & 0 & 0 \\ 0 & E_{\theta\theta} & 0 \\ 0 & 0 & E_{zz} \end{bmatrix} = \begin{bmatrix} \frac{1}{2}(\lambda_r^2 - 1) & 0 & 0 \\ 0 & \frac{1}{2}(\lambda_\theta^2 - 1) & 0 \\ 0 & 0 & \frac{1}{2}(\lambda_z^2 - 1) \end{bmatrix} \quad (\text{A3})$$

where $E_{\theta\theta}$, E_{zz} and E_{rr} are circumferential, axial and radial Green strains, respectively; $\lambda_\theta = \frac{l}{l_0} = \sqrt{2E_{\theta\theta} + 1}$, $\lambda_z = \frac{L}{L_0} = \sqrt{2E_{zz} + 1}$, and $\lambda_r = \frac{1}{\lambda_\theta \lambda_z}$ (given the material incompressibility, i.e., $\lambda_r \lambda_\theta \lambda_z = 1$) represent the corresponding stretch ratios (l and l_0 are the circumferential lengths in loaded and zero-stress states; and L and L_0 are the axial lengths in loaded and no-load states). The material incompressibility results in the following equation:

$$R = \sqrt{(r^2 - r_i^2)\chi\lambda_z + R_i^2} \quad (\text{A4})$$

Strain energy function: The 3D passive and active strain energy functions ($W_{passive}$ and W_{active} , respectively) are written as:

$$\begin{aligned} W_{passive} &= \frac{1}{2} C_1 [e^Q - 1] \\ W_{active} &= C_2 \left[\text{Erf} \left(\frac{\lambda_\theta}{b_1} + \frac{\lambda_z}{b_2} + \frac{\lambda_r}{b_3} - b' \right) - 1 \right] \end{aligned} \quad (\text{A5})$$

where $Q = a_1 E_{\theta\theta}^2 + a_2 E_{zz}^2 + a_3 E_{rr}^2 + 2a_4 E_{\theta\theta} E_{zz} + 2a_5 E_{zz} E_{rr} + 2a_6 E_{rr} E_{\theta\theta}$ and $b' = \frac{b_4}{b_1} + \frac{b_5}{b_2} + \frac{b_6}{b_3}$; $C_1, C_2, a_1 - a_6$

and $b_1 - b_6$ are material constants; and $\text{Erf}(X)$ is the Gauss error function. $W_{passive}$ refers to $W_{passive}^{IM}$ or $W_{passive}^A$ while W_{active} represents W_{active}^{IM} because K^+ -induced active strain energy function is only applied to the intima-media layer with SMCs.

The 3D passive and active 2nd PK stresses are written as:

$$\begin{aligned} S_{\theta\theta_{passive}} &= \frac{\partial W_{passive}}{\partial E_{\theta\theta}} = C_1 (a_1 E_{\theta\theta} + a_4 E_{zz} + a_6 E_{rr}) (e^Q) \\ S_{zz_{passive}} &= \frac{\partial W_{passive}}{\partial E_{zz}} = C_1 (a_2 E_{zz} + a_4 E_{\theta\theta} + a_5 E_{rr}) (e^Q) \\ S_{rr_{passive}} &= \frac{\partial W_{passive}}{\partial E_{rr}} = C_1 (a_3 E_{rr} + a_5 E_{zz} + a_6 E_{\theta\theta}) (e^Q) \\ S_{\theta\theta_{active}} &= \frac{\partial W_{active}}{\partial E_{\theta\theta}} = \frac{2C_2}{b_1 \sqrt{\pi} \sqrt{2E_{\theta\theta} + 1}} \exp \left[- \left(\frac{\sqrt{2E_{\theta\theta} + 1}}{b_1} + \frac{\sqrt{2E_{zz} + 1}}{b_2} + \frac{\sqrt{2E_{rr} + 1}}{b_3} - b' \right)^2 \right] \\ S_{zz_{active}} &= \frac{\partial W_{active}}{\partial E_{zz}} = \frac{2C_2}{b_2 \sqrt{\pi} \sqrt{2E_{zz} + 1}} \exp \left[- \left(\frac{\sqrt{2E_{\theta\theta} + 1}}{b_1} + \frac{\sqrt{2E_{zz} + 1}}{b_2} + \frac{\sqrt{2E_{rr} + 1}}{b_3} - b' \right)^2 \right] \\ S_{rr_{active}} &= \frac{\partial W_{active}}{\partial E_{rr}} = \frac{2C_2}{b_3 \sqrt{\pi} \sqrt{2E_{rr} + 1}} \exp \left[- \left(\frac{\sqrt{2E_{\theta\theta} + 1}}{b_1} + \frac{\sqrt{2E_{zz} + 1}}{b_2} + \frac{\sqrt{2E_{rr} + 1}}{b_3} - b' \right)^2 \right] \end{aligned} \quad (\text{A6})$$

The 3D 1st PK stresses at passive and active states are written as:

$$\begin{aligned}
T_{\theta\theta_{\text{passive}}} &= \lambda_{\theta} S_{\theta\theta_{\text{passive}}} = C_1 \lambda_{\theta} (a_1 E_{\theta\theta} + a_4 E_{zz} + a_6 E_{rr}) (e^Q) \\
T_{zz_{\text{passive}}} &= \lambda_z S_{zz_{\text{passive}}} = C_1 \lambda_z (a_2 E_{zz} + a_4 E_{\theta\theta} + a_5 E_{rr}) (e^Q) \\
T_{rr_{\text{passive}}} &= \lambda_r S_{rr_{\text{passive}}} = C_1 \lambda_r (a_3 E_{rr} + a_5 E_{zz} + a_6 E_{\theta\theta}) (e^Q) \\
T_{\theta\theta_{\text{active}}} &= \lambda_{\theta} S_{\theta\theta_{\text{active}}} = \frac{2C_2}{b_1 \sqrt{\pi}} \exp \left[- \left(\frac{\sqrt{2E_{\theta\theta} + 1}}{b_1} + \frac{\sqrt{2E_{zz} + 1}}{b_2} + \frac{\sqrt{2E_{rr} + 1}}{b_3} - b \right)^2 \right] \\
T_{zz_{\text{active}}} &= \lambda_z S_{zz_{\text{active}}} = \frac{2C_2}{b_2 \sqrt{\pi}} \exp \left[- \left(\frac{\sqrt{2E_{\theta\theta} + 1}}{b_1} + \frac{\sqrt{2E_{zz} + 1}}{b_2} + \frac{\sqrt{2E_{rr} + 1}}{b_3} - b \right)^2 \right] \\
T_{rr_{\text{active}}} &= \lambda_r S_{rr_{\text{active}}} = \frac{2C_2}{b_3 \sqrt{\pi}} \exp \left[- \left(\frac{\sqrt{2E_{\theta\theta} + 1}}{b_1} + \frac{\sqrt{2E_{zz} + 1}}{b_2} + \frac{\sqrt{2E_{rr} + 1}}{b_3} - b \right)^2 \right]
\end{aligned} \tag{A7}$$

Equations (A7) and (A8) were used to determine Piola-Kirchhoff stresses.

APPENDIX B

The equilibrium equation in cylindrical coordinate is given as:

$$\frac{\partial \sigma_r}{\partial r} + \frac{\sigma_r - \sigma_\theta}{r} = 0 \quad (\text{B1})$$

where σ_r and σ_θ are radial and circumferential Cauchy stresses, respectively. The passive Cauchy stress tensor is written as:

$$\sigma_{passive} = F \cdot \frac{\partial W_{passive}}{\partial E} \cdot F^T - PI \quad (\text{B2})$$

where P is the unknown Lagrange multiplier which needs to be determined from boundary conditions. The K^+ -induced 3D active strain energy function was used to model the fully contraction of the intima-media layer, i.e., $W_{total}^{IM} = W_{passive}^{IM} + W_{active}^{IM}$. The total Cauchy stress in the intima-media layer is given by

$$\sigma_{total} = F \cdot \frac{\partial (W_{passive}^{IM} + W_{active}^{IM})}{\partial E} \cdot F^T - PI \quad (\text{B3})$$

The adventitia layer does not contribute to the active contraction of the artery and thus only the passive strain energy is considered in the adventitia layer, i.e., $W_{total}^A = W_{passive}^A$.

The boundary conditions at the inner and outer surfaces of vessel wall are:

$$\sigma_r|_{r=r_i^{IM}} = -p \quad \text{and} \quad \sigma_r|_{r=r_o^A} = 0 \quad (\text{B4})$$

where p equals to 80 mmHg. Subscripts 'i' and 'o' refer to inner and outer boundaries. An additional boundary condition is the stress balance at the interface between intima-media and adventitia layers:

$$\sigma_r|_{r=r_o^{IM}} = \sigma_r|_{r=r_i^A} \quad (\text{B5})$$

Solving Eq. (B1) with boundary conditions, radial, circumferential, and axial stress components in the intima-media layer are given by:

$$\begin{cases} \sigma_r^{IM} = \int_{r_i^{IM}}^r \left(\lambda_\theta^2 \frac{\partial W^{IM}}{\partial E_{\theta\theta}} - \lambda_r^2 \frac{\partial W^{IM}}{\partial E_{rr}} \right) \frac{1}{r} dr - p \\ \sigma_\theta^{IM} = \sigma_r^{IM} + \lambda_\theta^2 \frac{\partial W^{IM}}{\partial E_{\theta\theta}} - \lambda_r^2 \frac{\partial W^{IM}}{\partial E_{rr}} \\ \sigma_z^{IM} = \sigma_r^{IM} + \lambda_z^2 \frac{\partial W^{IM}}{\partial E_{zz}} - \lambda_r^2 \frac{\partial W^{IM}}{\partial E_{rr}} \end{cases} \quad (\text{B6})$$

From Eq. (B5), we can obtain:

$$\sigma_r|_{r=r_i^A} = \sigma_r|_{r=r_o^{IM}} = \int_{r_i^{IM}}^{r_o^{IM}} \left(\lambda_\theta^2 \frac{\partial W^{IM}}{\partial E_{\theta\theta}} - \lambda_r^2 \frac{\partial W^{IM}}{\partial E_{rr}} \right) \frac{1}{r} dr - p \quad (\text{B7})$$

Solving Eq. (B1) with boundary conditions, radial, circumferential, and axial stress components in the adventitia layer are given by:

$$\begin{cases} \sigma_r^A = \int_{r_i^A}^r \left(\lambda_\theta^2 \frac{\partial W^A}{\partial E_{\theta\theta}} - \lambda_r^2 \frac{\partial W^A}{\partial E_{rr}} \right) \frac{1}{r} dr + \int_{r_i^{IM}}^{r_o^{IM}} \left(\lambda_\theta^2 \frac{\partial W^{IM}}{\partial E_{\theta\theta}} - \lambda_r^2 \frac{\partial W^{IM}}{\partial E_{rr}} \right) \frac{1}{r} dr - p \\ \sigma_\theta^A = \sigma_r^A + \lambda_\theta^2 \frac{\partial W^A}{\partial E_{\theta\theta}} - \lambda_r^2 \frac{\partial W^A}{\partial E_{rr}} \\ \sigma_z^A = \sigma_r^A + \lambda_z^2 \frac{\partial W^A}{\partial E_{zz}} - \lambda_r^2 \frac{\partial W^A}{\partial E_{rr}} \end{cases} \quad (\text{B8})$$

Given the appropriate strain energy functions, Equations (B1-B8) were used to solve the transmural stress-strain relationship from stress-free to loaded vessel wall at both passive and active states.