

Supplemental Information: Connection adaption for control of networked mobile chaotic agents

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THE IMPACT OF CONTACT RADIUS

Figure 1(a) shows the length of largest chain, $l_{\max}$, as a function of the contact radius r for the case of $v = 0$. We observe the inverse correlation between them, and the inset in Fig. 1(a) highlights that the curve $l_{\max}$ vs. $1/r$ displays indeed a linear fit, with a slope around 1. As pointed out in the main text, for a certain coupling strength σ , when $l_{\max}$ does not exceed $m_{\text{th}}(\sigma)$ the whole network can be controlled. As increasing r causes a decrease of $l_{\max}$, an enlargement of the feasible range of σ for control should also be determined. The latter is confirmed in Fig. 1(b), where $\langle \delta \rangle$ is reported vs. σ , for different r values. The striking similarity of the trends reported in Fig. 1(b) here and in Fig. 2 in the main text suggests that the effect of increasing the velocity v is actually equivalent to that of reducing the length of the longest chain $l_{\max}$. Figure 1(b) suggests the existence of an upper bound of σ , denoted as σ_{th} , above which $\langle \delta \rangle$ diverges, for different r . The relation between r and σ_{th} is presented in Fig. 1(c). Combining Figs. 1(a) and (c), one obtains the relation between σ_{th} and $l_{\max}$ as shown in Fig. 1(d), where the function of $m_{\text{th}}(\sigma)$ is also plotted for comparison. We can see that $l_{\max}(\sigma_{\text{th}})$ matches well with $m_{\text{th}}(\sigma)$, conforming to our conclusion in the main text that the control performance for a static network is determined by the longest chain.

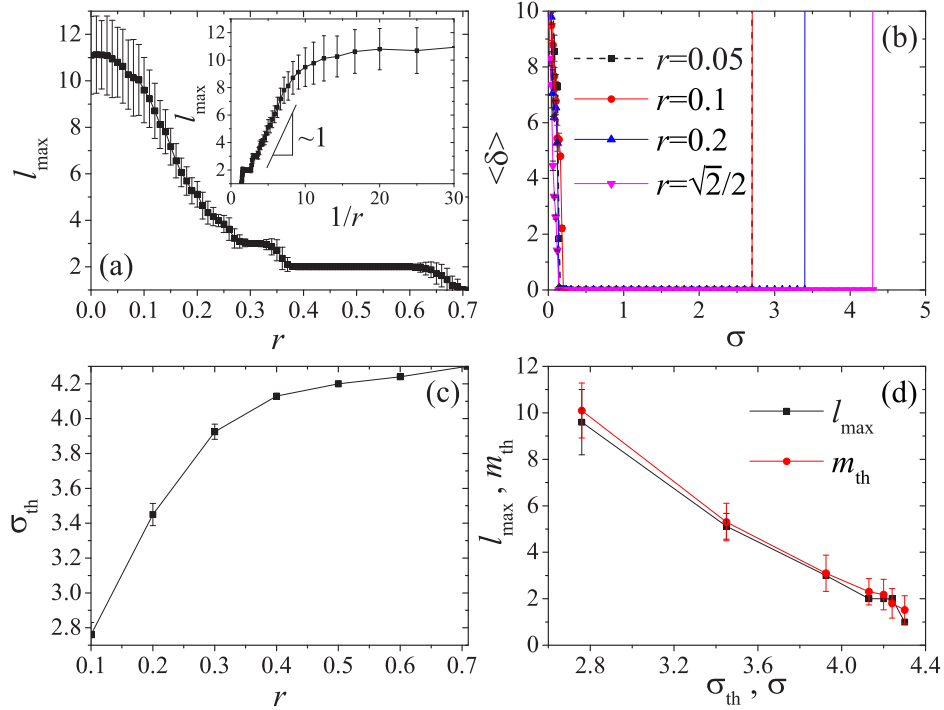


FIG. 1: (Color online). (a) Length of the longest chain $l_{\max}$ as a function of r . $l_{\max}$ is around 11 at $r < 0.1$. Inset: $l_{\max}$ vs. $1/r$. (b) $\langle \delta \rangle$ vs. σ for $r = 0.05, 0.1, 0.2$, and $\sqrt{2}/2$, and for $v = 0$. Note that when $r = \sqrt{2}/2$ all the agents connect uniformly to the GA. (c) The relationship between r and the threshold σ_{th} , above which $\langle \delta \rangle$ diverges. (d) The relationship between $l_{\max}$ and σ_{th} , which is produced with the help of panels (a) and (c), and the relation between m_{th} and σ , reported already in Fig. 3(c) in the main text. Other parameters are the same as those in the main text.