

Robotic right ventricle is a biohybrid platform that simulates right ventricular function in (patho)physiological conditions and intervention

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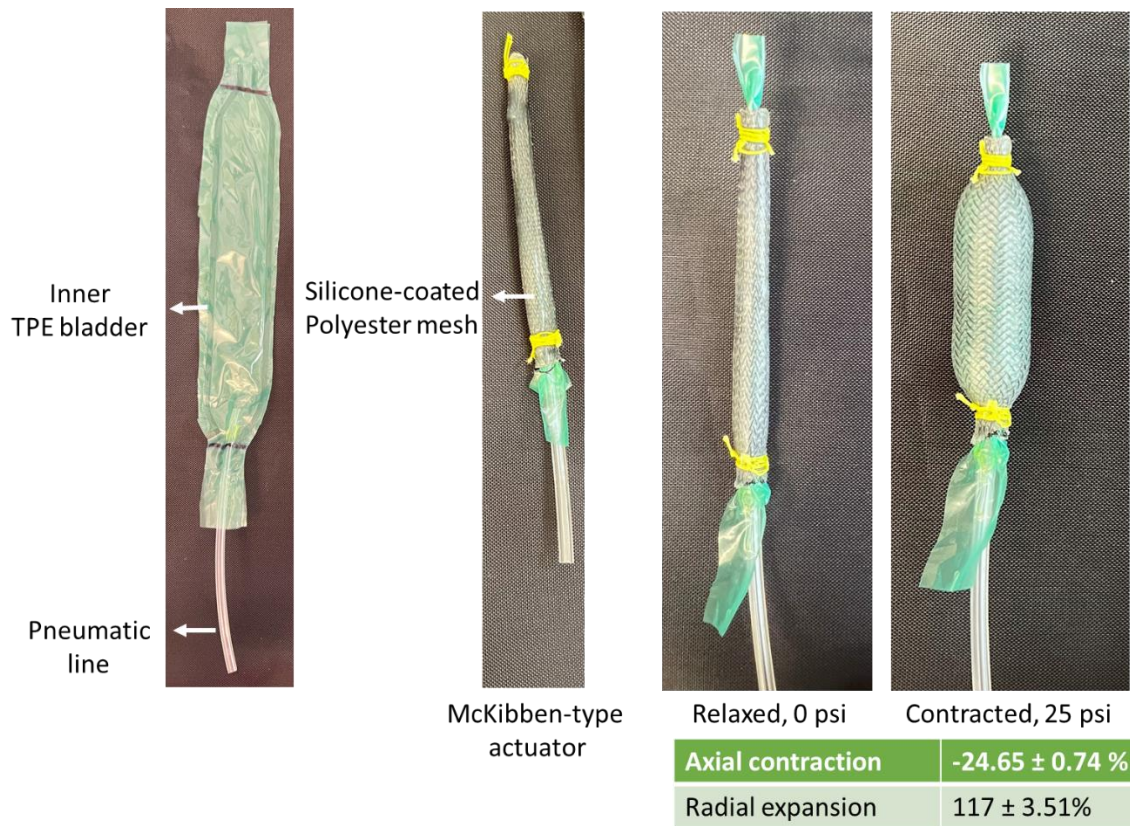
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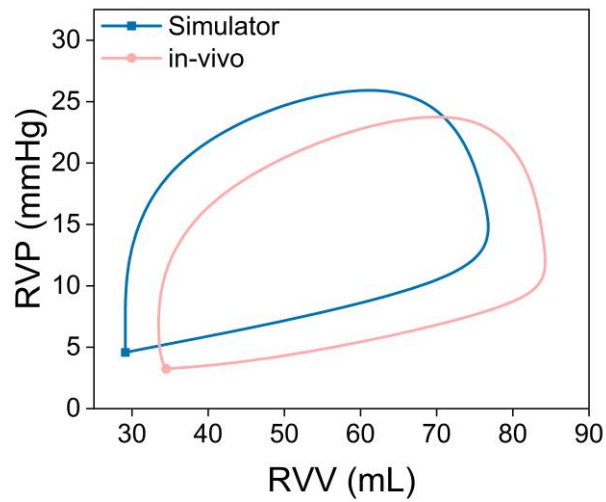
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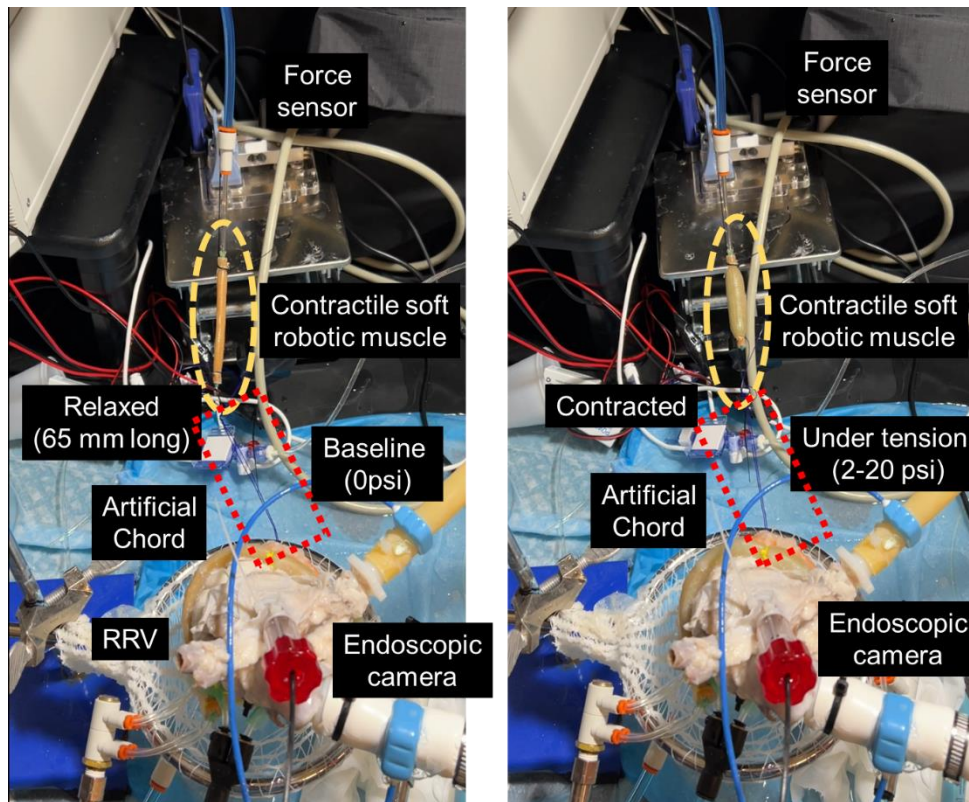
Source data for the main figures (Figs 2c-2f, 3d-3g, 4a-4b, 7a-7c, 8c, 8f, and 8i) and extended data (Figs 1, 4-6) are available in separate .xlsx files



Supplementary Figure 1: Fabrication and characterization of McKibben-type soft robotic actuators. TPE, thermoplastic elastomer.



Supplementary Figure 2: The representative pressure-volume loops of the robotic right ventricle (RRV) simulator vs. an *in vivo* porcine model over one cardiac cycle.



Supplementary Figure 3: Integrating a 65 mm McKibben soft robotic muscle into the robotic right ventricle (RRV), connecting it to the posterior leaflet chordae on one end and a force sensor on the other for recreating papillary muscle contraction on bench.

Supplementary Movie 1: Structural motion and flow profile of the RRV in a computational model. RRV, robotic right ventricle.

Supplementary Movie 2: Beating RRV in the *in vitro* mock circulatory flow loop recreating the right ventricular (RV) wall motion on a bench. RRV, robotic right ventricle.

Supplementary Movie 3: The wall motion and valve function of the RRV using magnetic resonance imaging (MRI), echocardiography, and endoscopic imaging. RRV, robotic right ventricle.

Supplementary Movie 4: Simulating various disease conditions related to right ventricular (RV) volume overload, systolic failure, and pressure overload, such as tricuspid regurgitation, myocardial infarction, and pulmonary artery hypertension.

Supplementary Movie 5: The surgical implantation of prosthetic annuloplasty rings at the tricuspid annulus effectively establishes RRV as a suitable platform for testing right heart interventions and evaluating their hemodynamic consequences. RRV, robotic right ventricle.