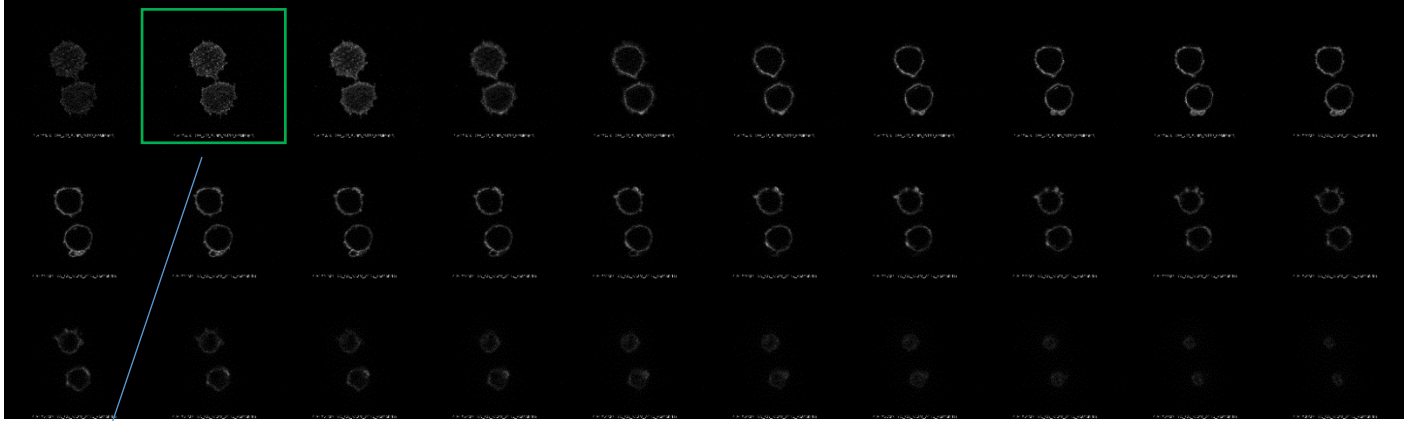
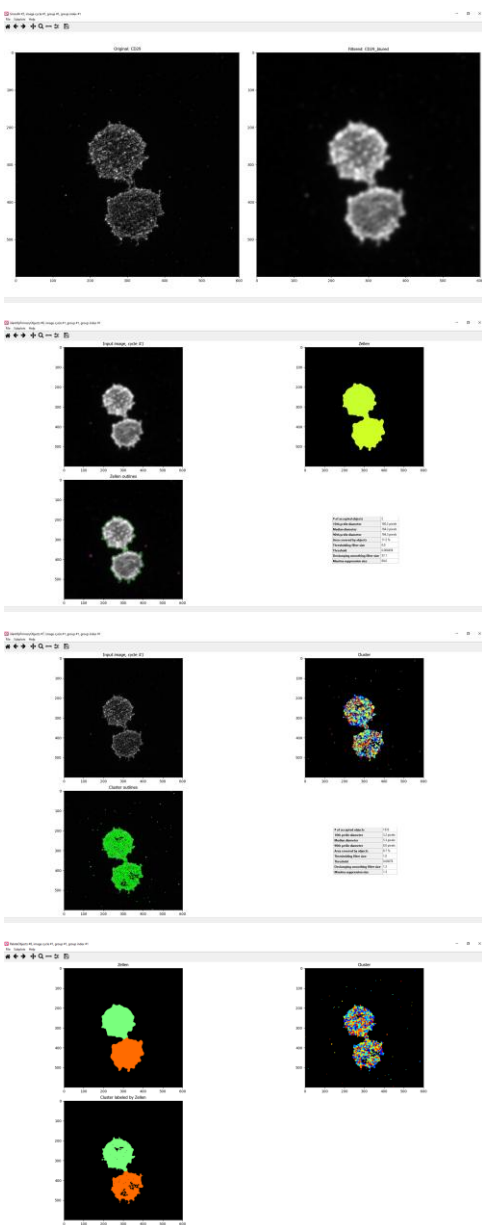




manual selection of the first in focus plane



Step: Blur

- To fuse neighbouring objects (to identify cell bodies)
- Remove background

Step: identify cells

- Filter by size (i.e. remove smaller debris)
- Filter objects touching the edges of the image

Step: identify cluster

- Filter by size
- declumping fused clusters

Step: relate clusters to identified cells

- to measure clusters per cell

Step: Export data



Step: rescale image intensity

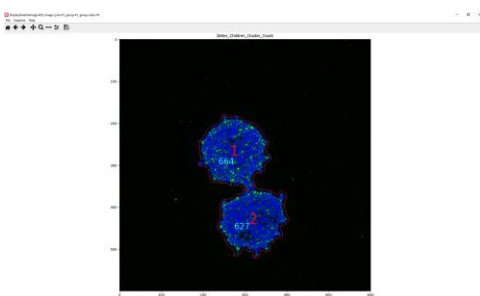
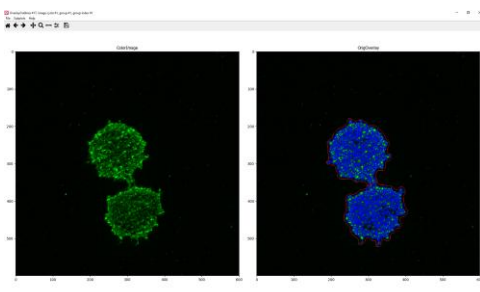
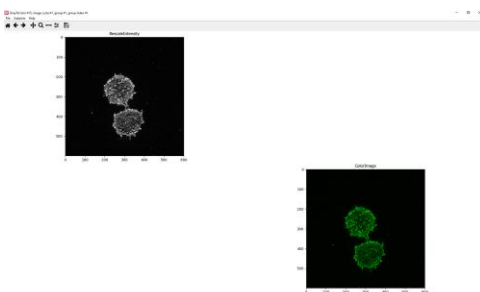
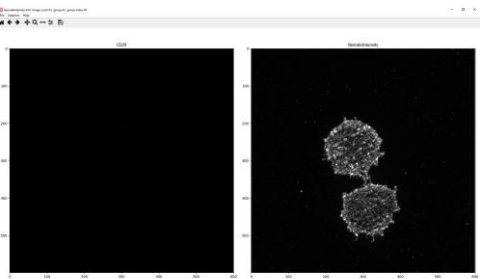
- preparation for a later merged image

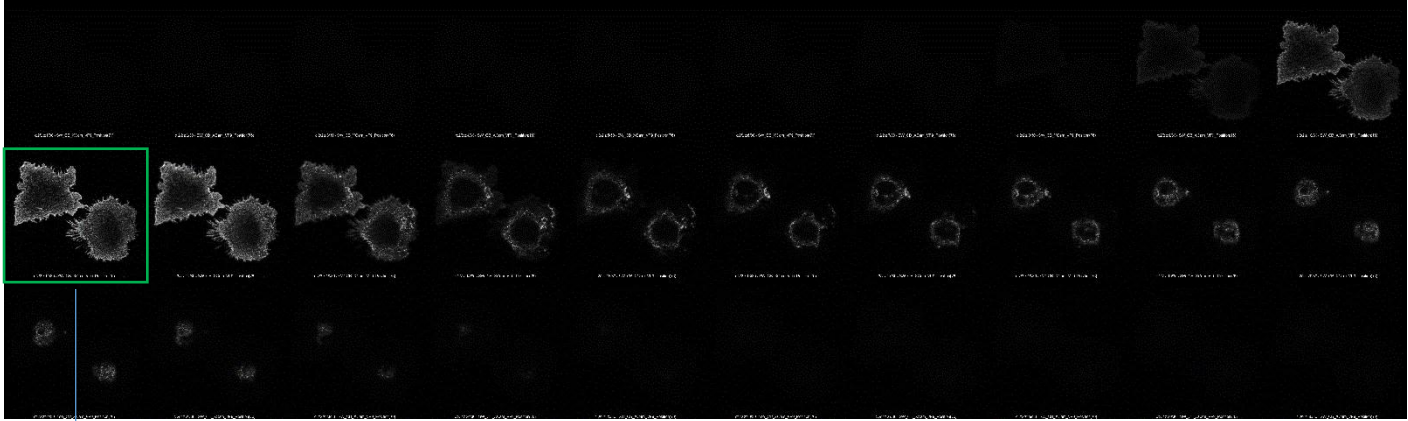
Step: apply green look up table

Step: superimpose object borders

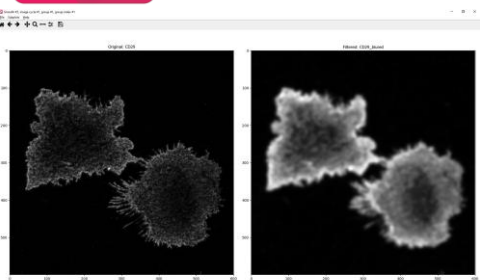
- blue cluster
- red cell borders

Step: superimpose data on image
and save file into the results folder



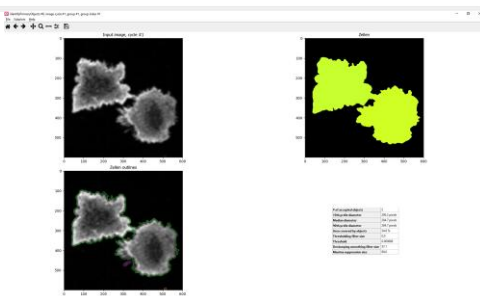


manual selection of the first in focus plane



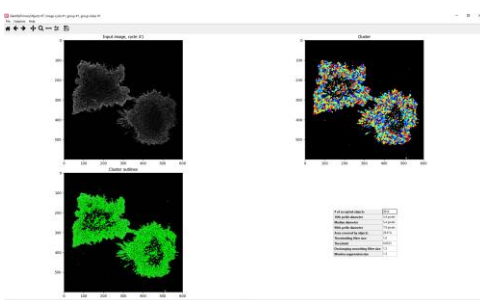
Step: Blur

- To fuse neighbouring objects (to identify cell bodies)
- Remove background



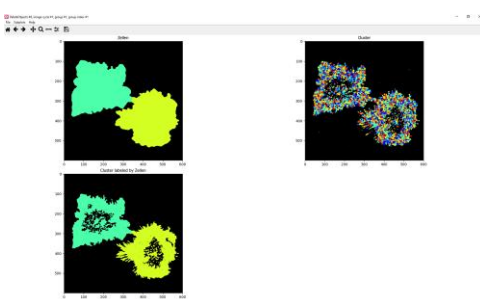
Step: identify cells

- Filter by size (i.e. remove smaller debris)
- Filter objects touching the edges of the image



Step: identify cluster

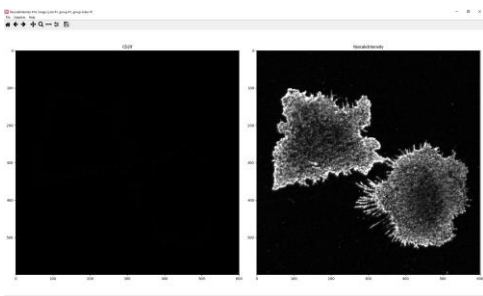
- Filter by size
- declumping fused clusters



Step: relate clusters to identified cells

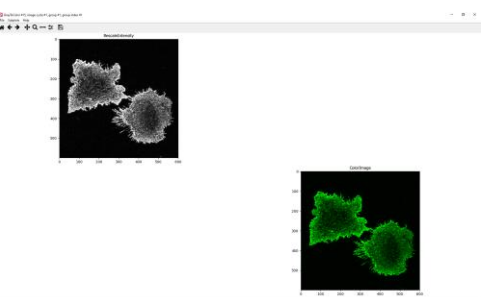
- to measure clusters per cell

Step: Export data

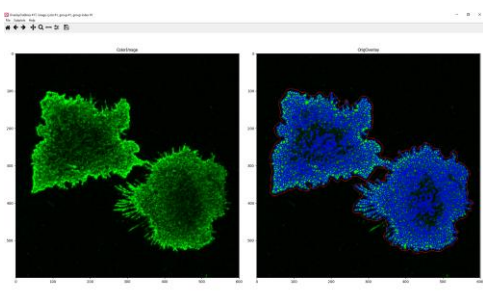


Step: rescale image intensity

- preparation for a later merged image

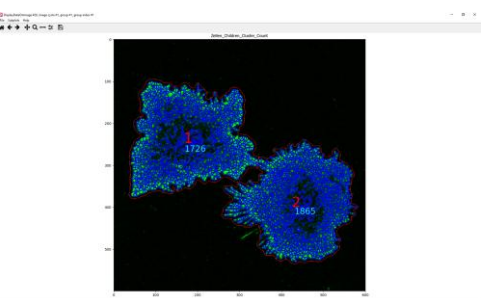


Step: apply green look up table



Step: superimpose object borders

- blue cluster
- red cell borders



Step: superimpose data on image
and save file into the results folder